

# **Introduction to Computational Methods**

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**Institute for Computational  
Civil Engineering**

**Cracow University of Technology**

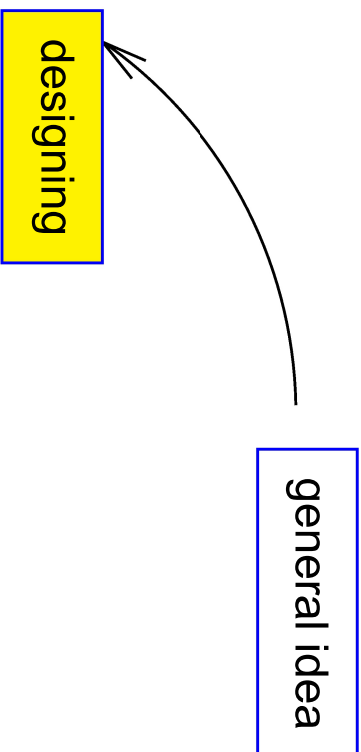
# *Designing and Modeling in Engineering*

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general idea

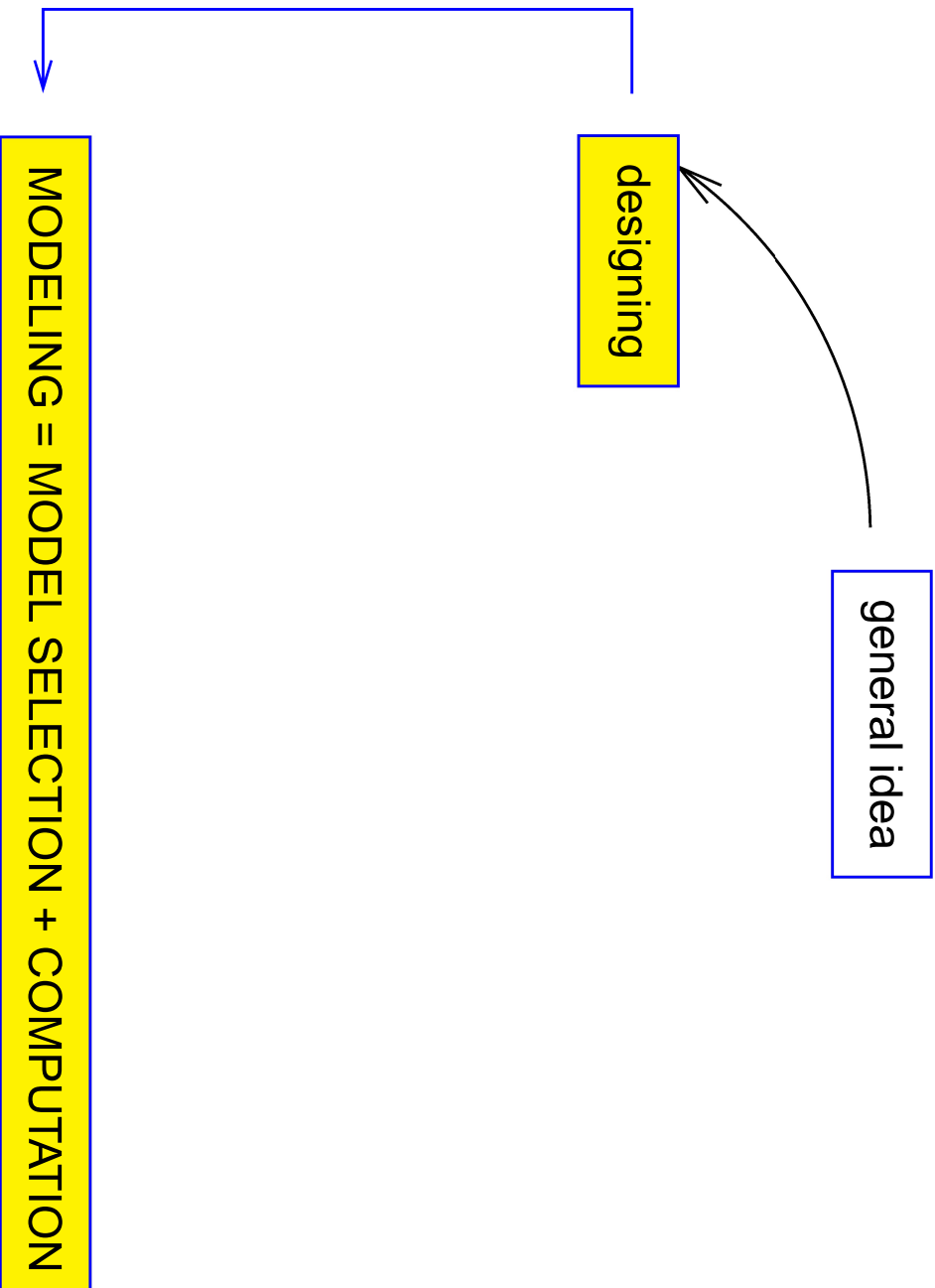
# *Designing and Modeling in Engineering*

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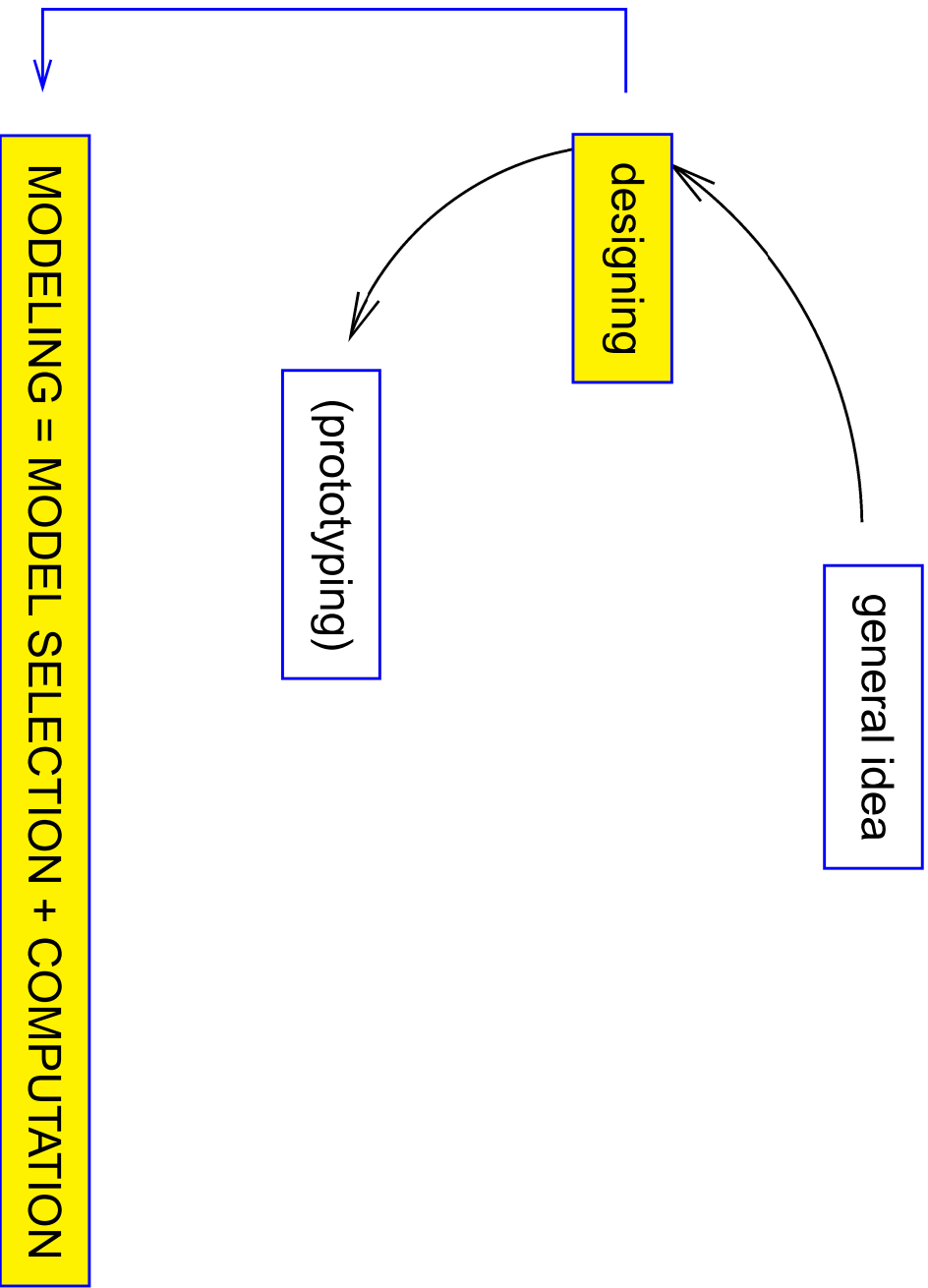
# *Designing and Modeling in Engineering*

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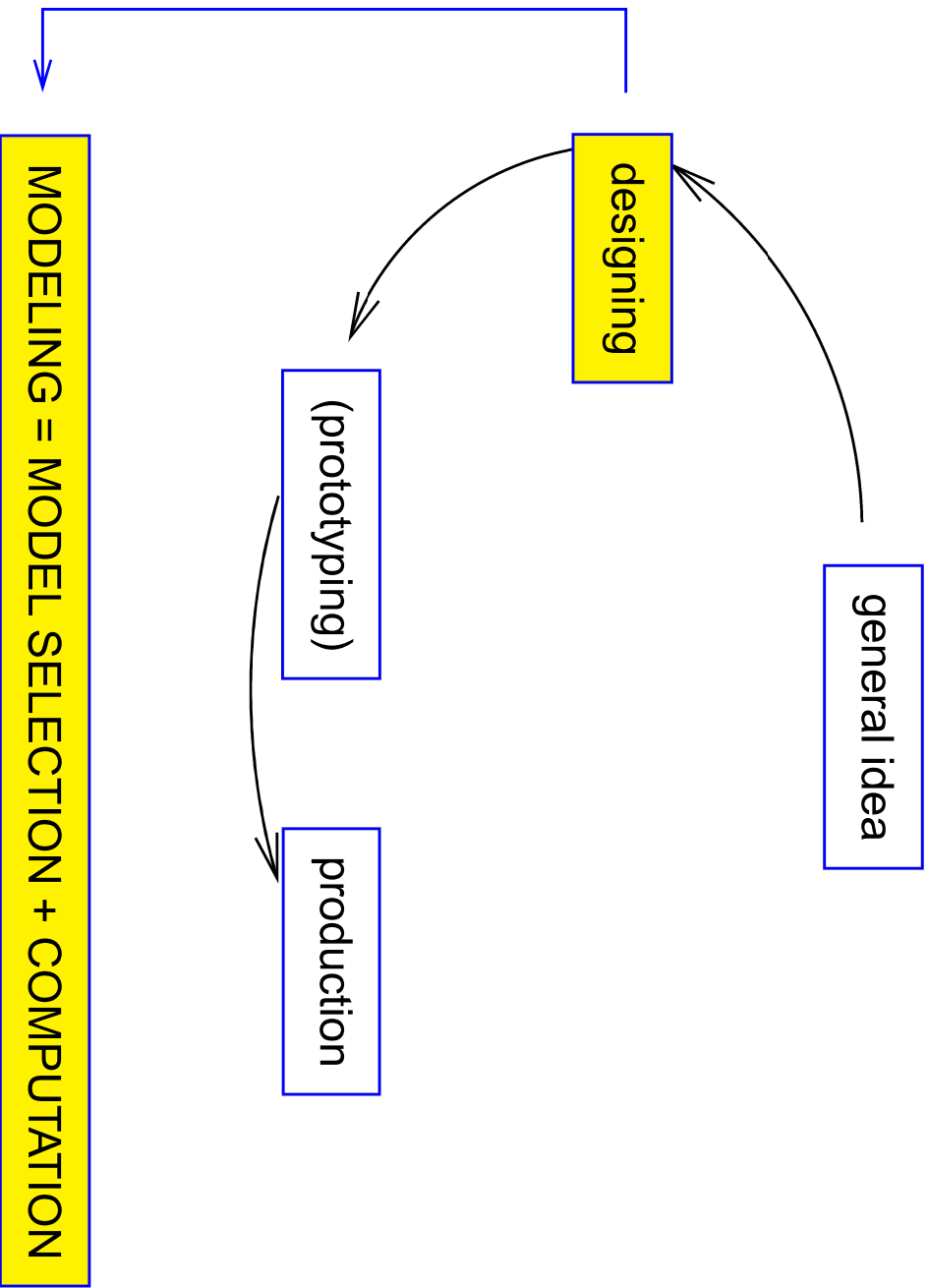
# *Designing and Modeling in Engineering*

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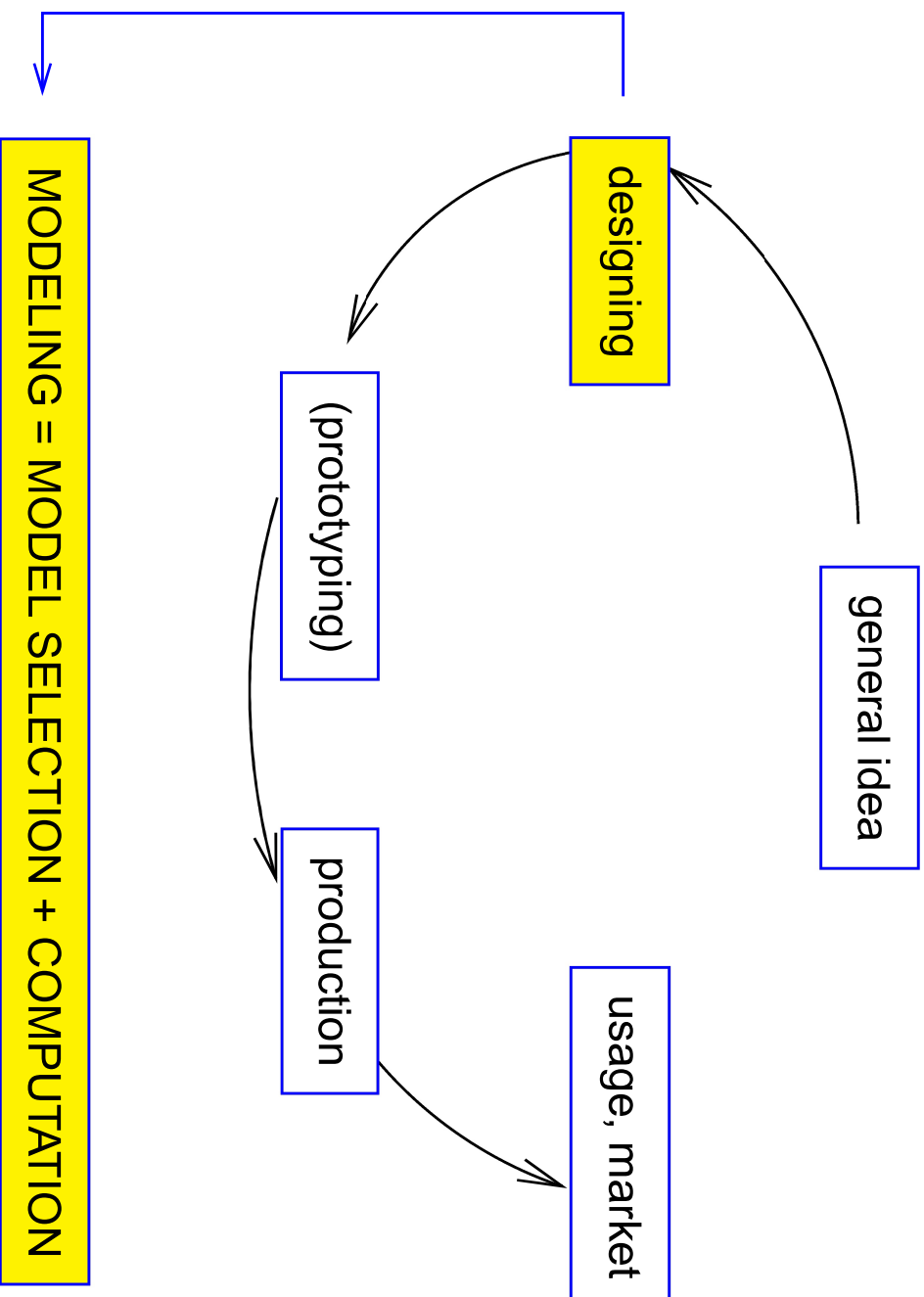
# *Designing and Modeling in Engineering*

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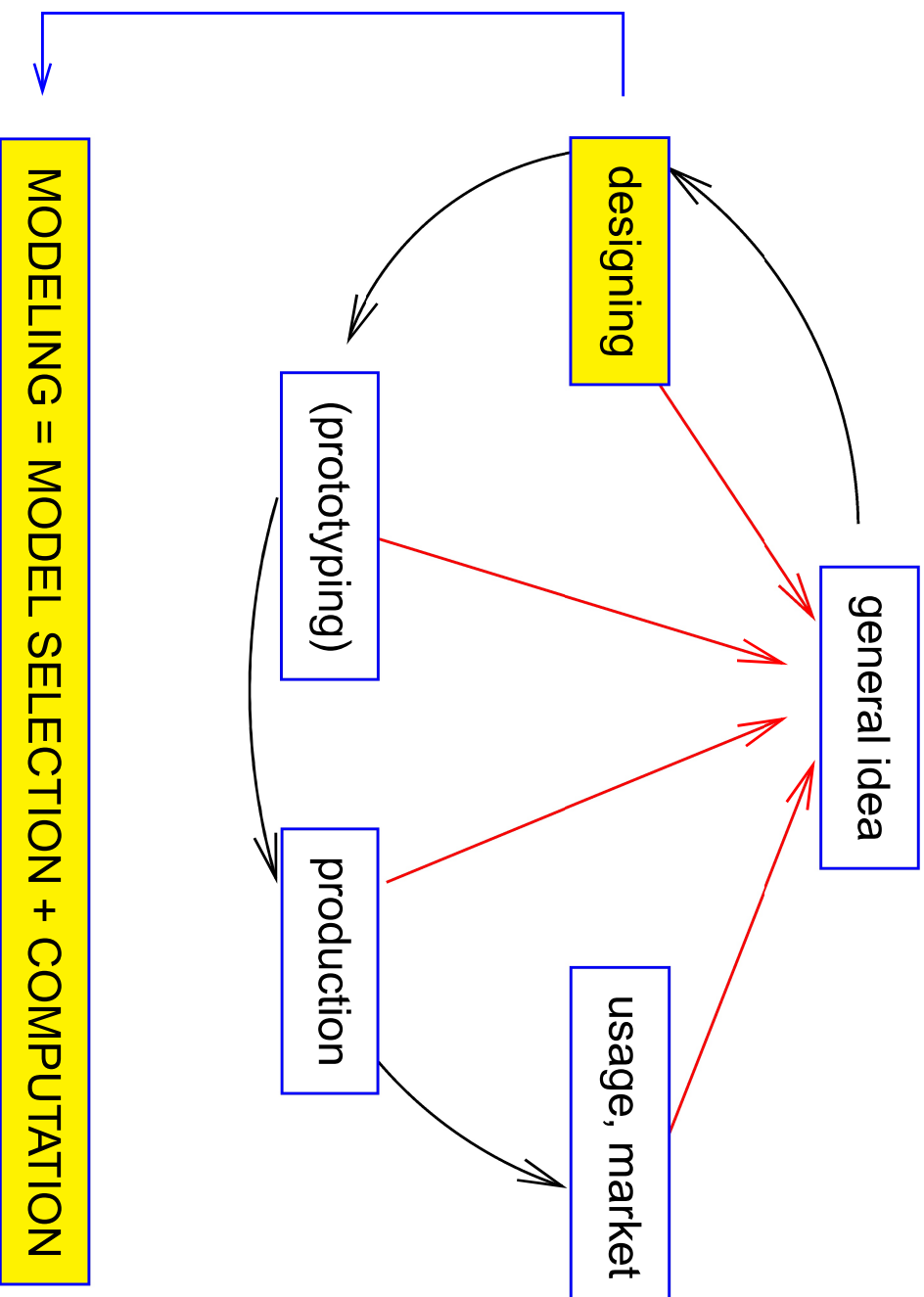
# Designing and Modeling in Engineering

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# Designing and Modeling in Engineering

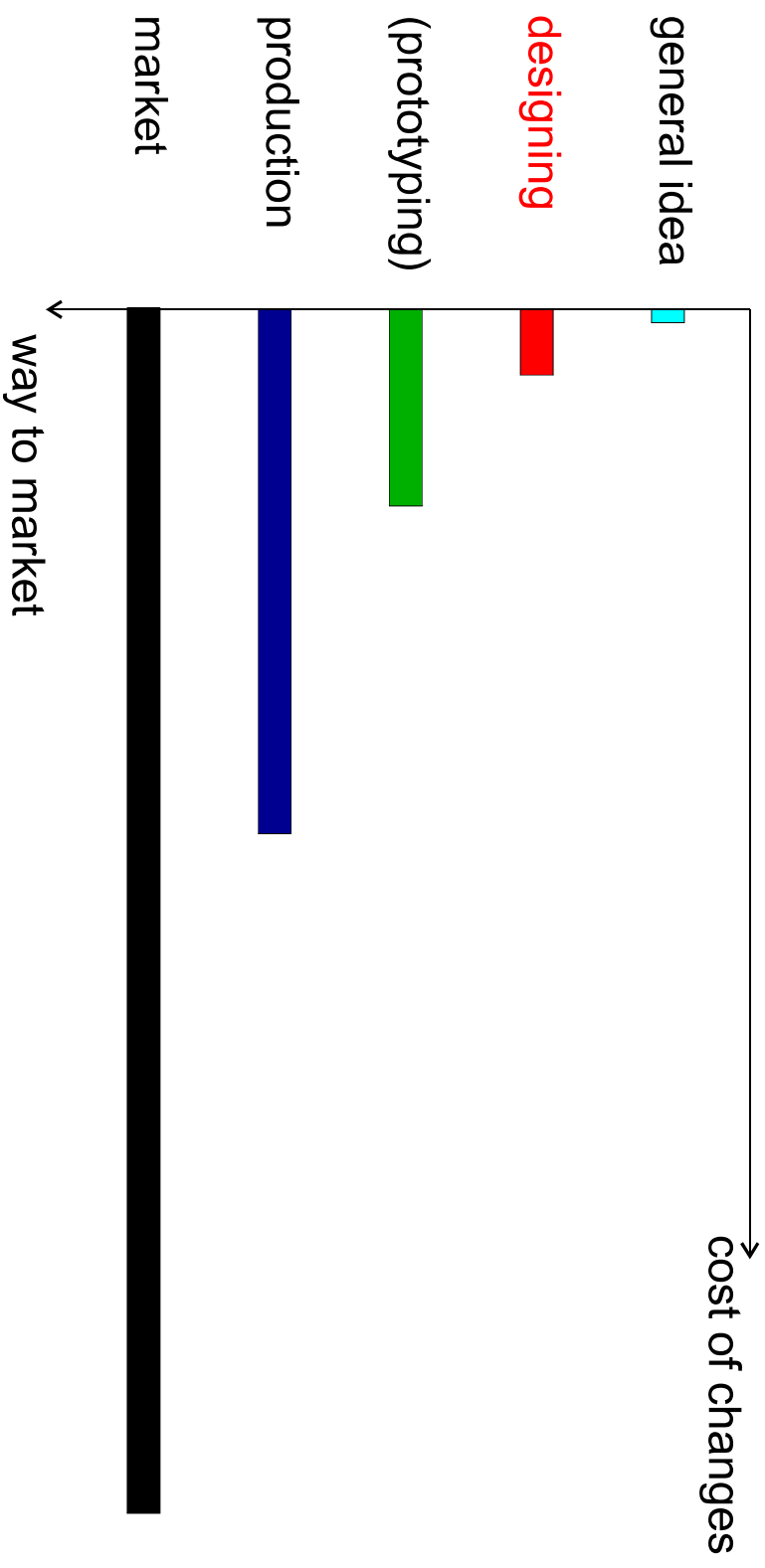
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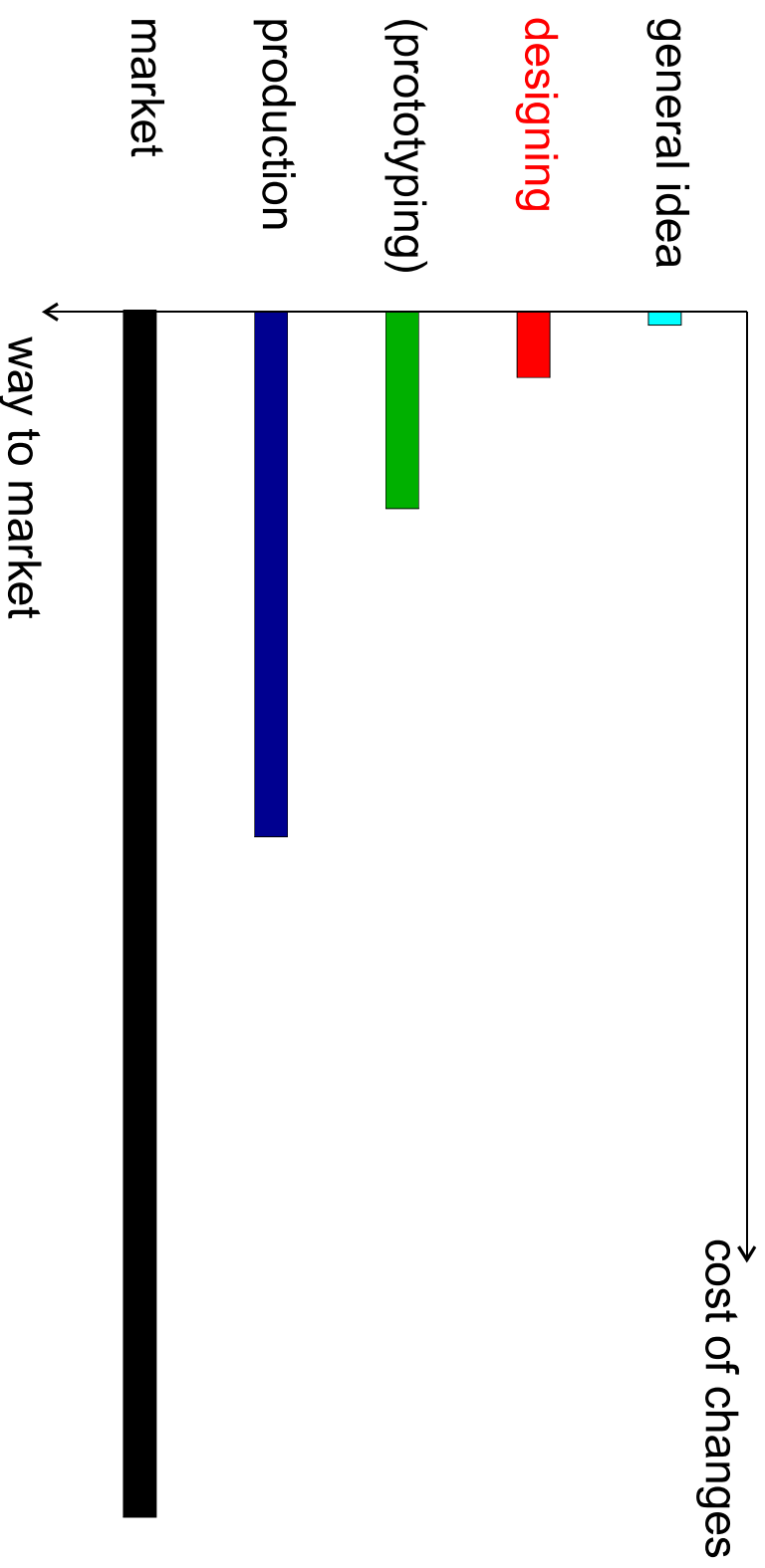
# *Designing and Modeling in Engineering*

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## *Designing and Modeling in Engineering*

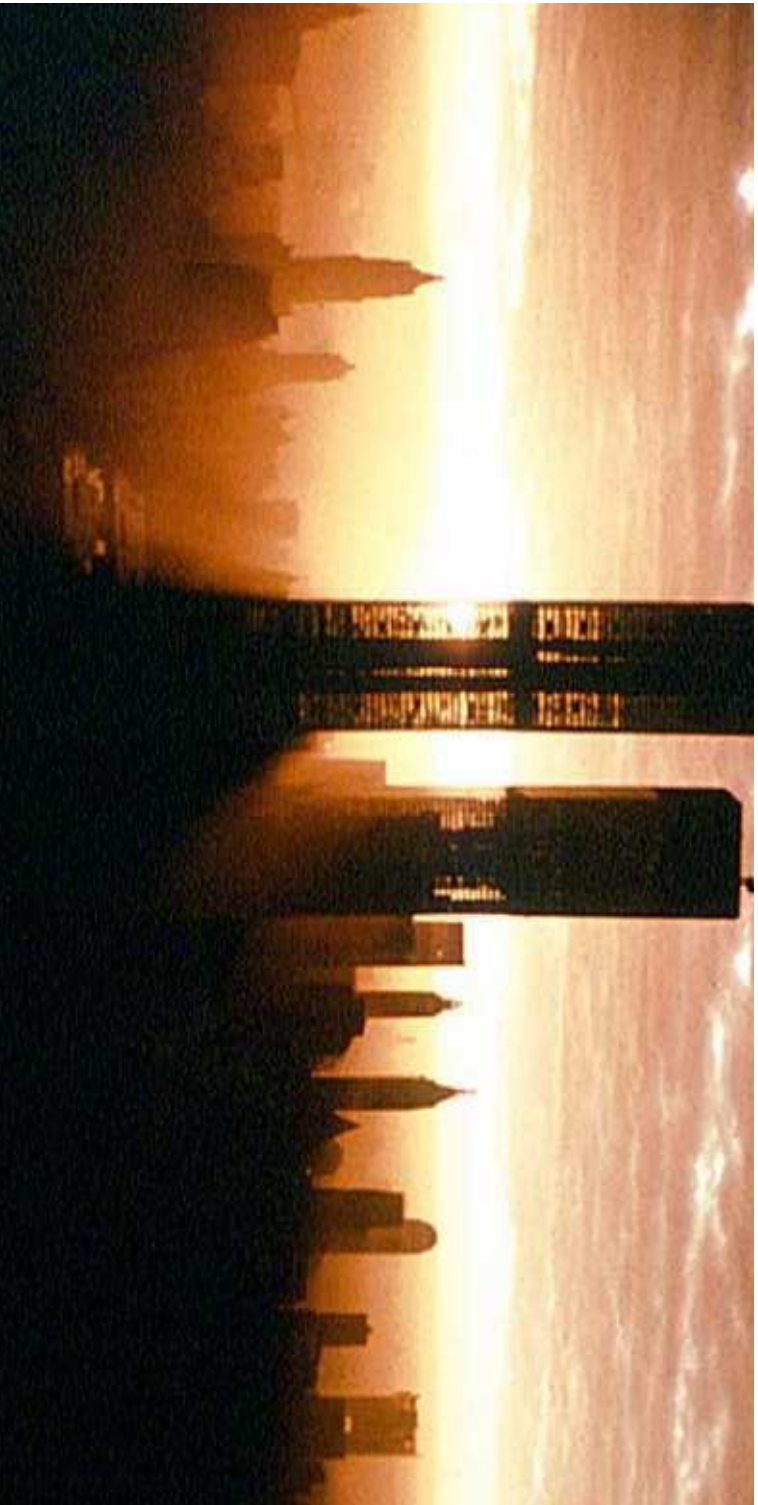
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A recent study sponsored by the United States Government concluded that enterprise-wide "... modeling and simulation are emerging as key technologies to support manufacturing in the 21st century, and no other technology offers more potential than modeling and simulation for improving products, perfecting processes, reducing design-to-manufacturing cycle time, and reducing product realization costs..."

## *Designing and Modeling in Engineering*

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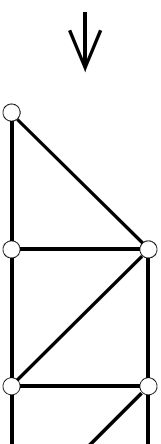


Design is **IMPERFECT**, **TRADE-OFFS** are required,  
**RISK** must be **ACCEPTED** but **MITIGATED**

# Modeling

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- Model selection for
  - object

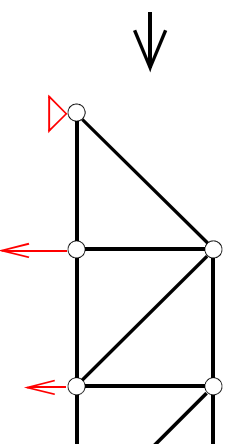


boundary value problem  
(initial)

# Modeling

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- Model selection for
  - object + boundary conditions (+ initial conditions)



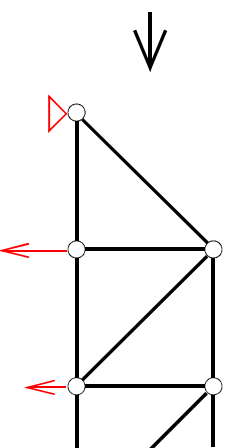
boundary value problem  
(initial)

# Modeling

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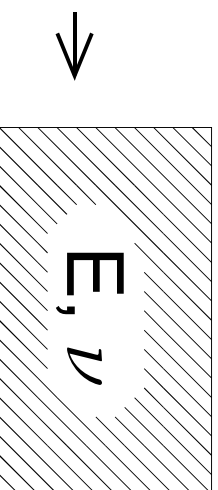
- Model selection for

- object + boundary conditions (+ initial conditions)



boundary value problem  
(initial)

- material



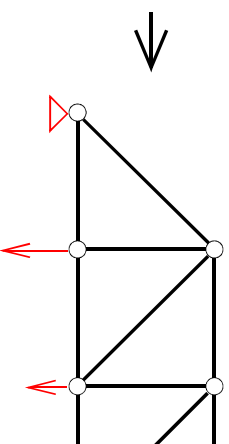
coefficients  
(eg. constant)

# Modeling

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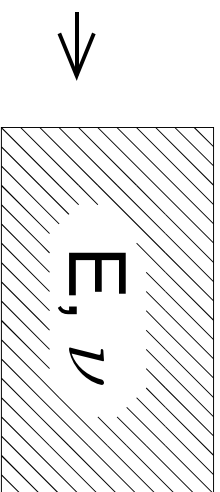
- Model selection for

- object + boundary conditions (+ initial conditions)



boundary value problem  
(initial)

- material



coefficients  
(eg. constant)

- values of parameters

*deterministic/stochastic distribution*

## A Mathematical Model

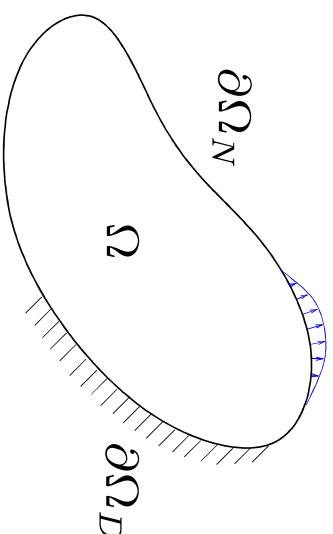
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- An example of a linear problem

Find function  $u(x) \in C^2(\Omega): \mathbb{R}^2 \ni \Omega \rightarrow \mathbb{R}$  such that

$$\left\{ \begin{array}{l} k\Delta u = -q \quad \text{in } \Omega \\ u = 0 \quad \text{on } \partial\Omega_D \\ k\frac{\partial u}{\partial n} = \hat{g} \quad \text{on } \partial\Omega_N \end{array} \right.$$

or



$$u \in H_0^1; \quad \int_{\Omega} k\nabla v \circ \nabla u \, d\Omega = \int_{\Omega} vq \, d\Omega + \int_{\partial\Omega_N} v\hat{g} \, ds \quad \forall v \in H_0^1$$

- in general

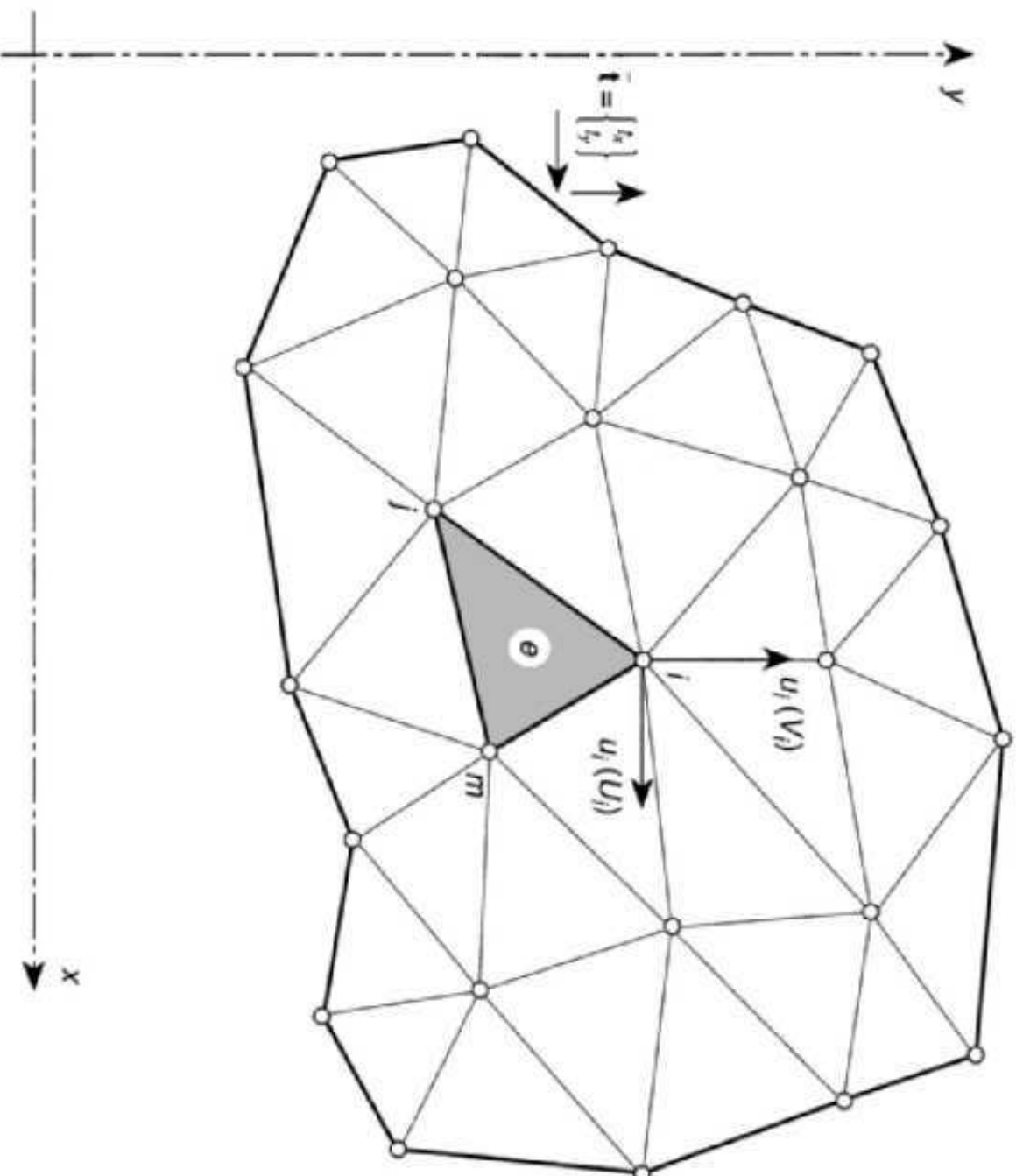
$$L(u) = -q \quad (+ b.c.)$$

or

$$b(v, u) = l(v)$$

$$\forall v \in V$$

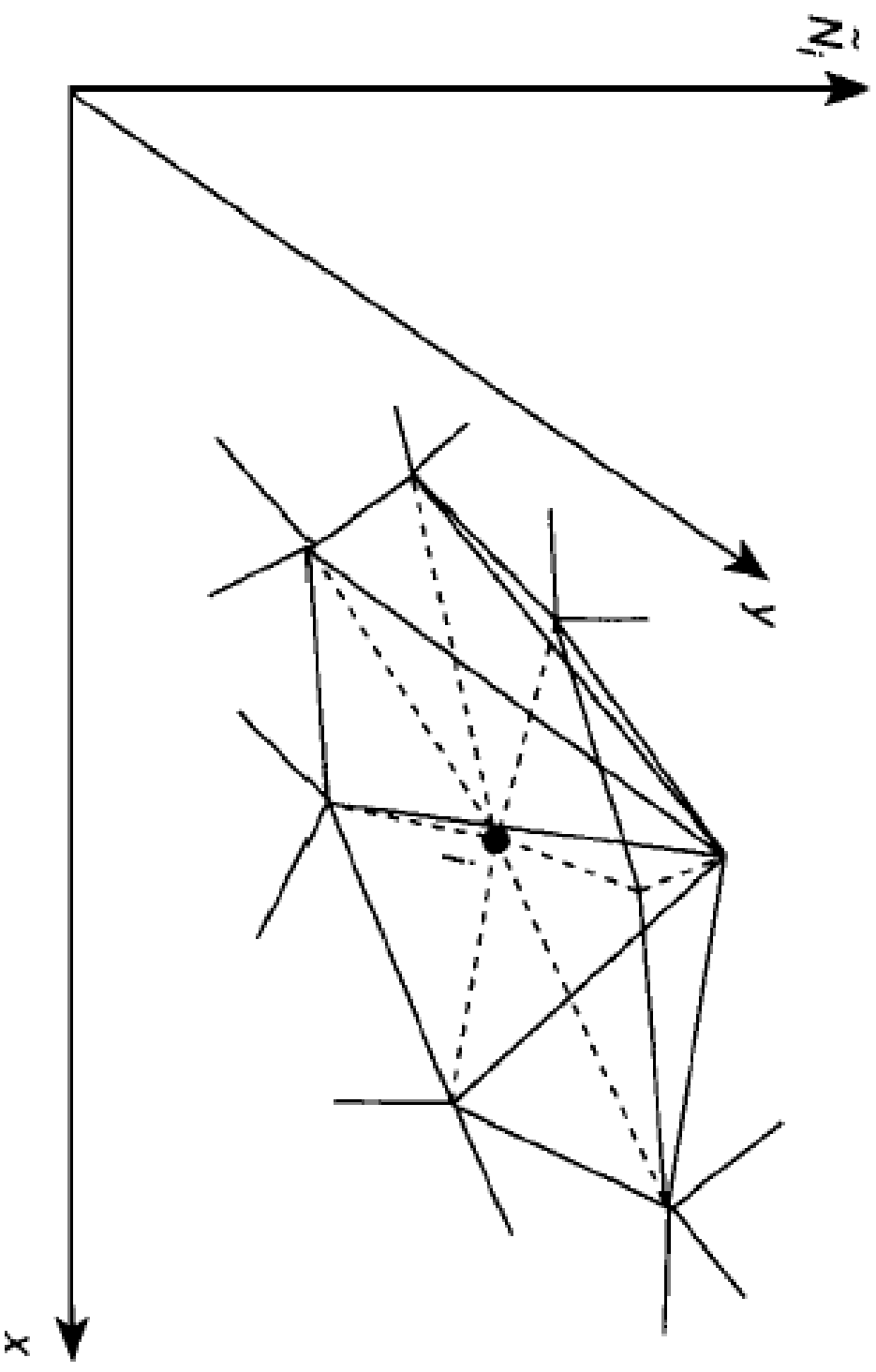




**Fig. 2.1** A plane stress region divided into finite elements.

## Shape functions

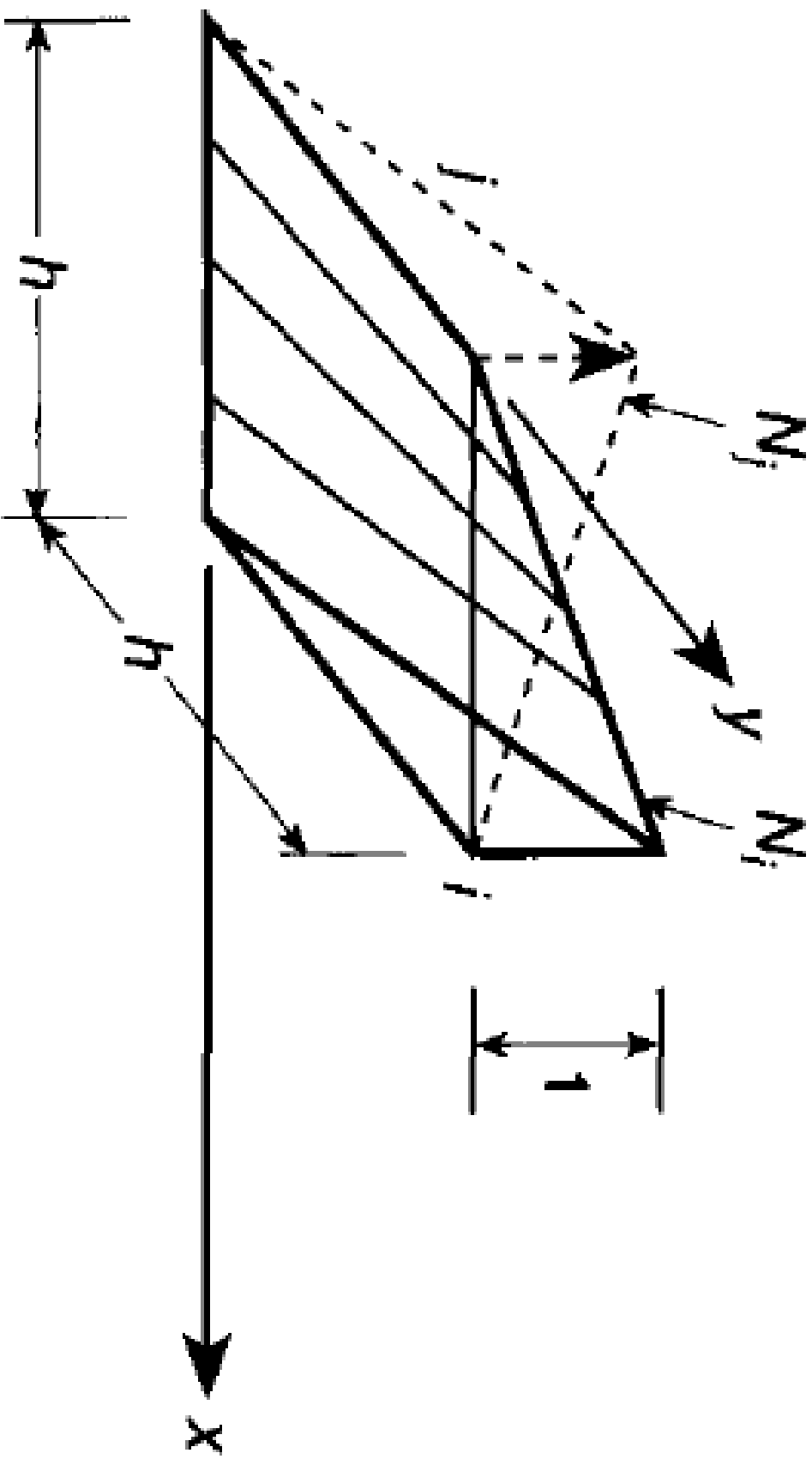
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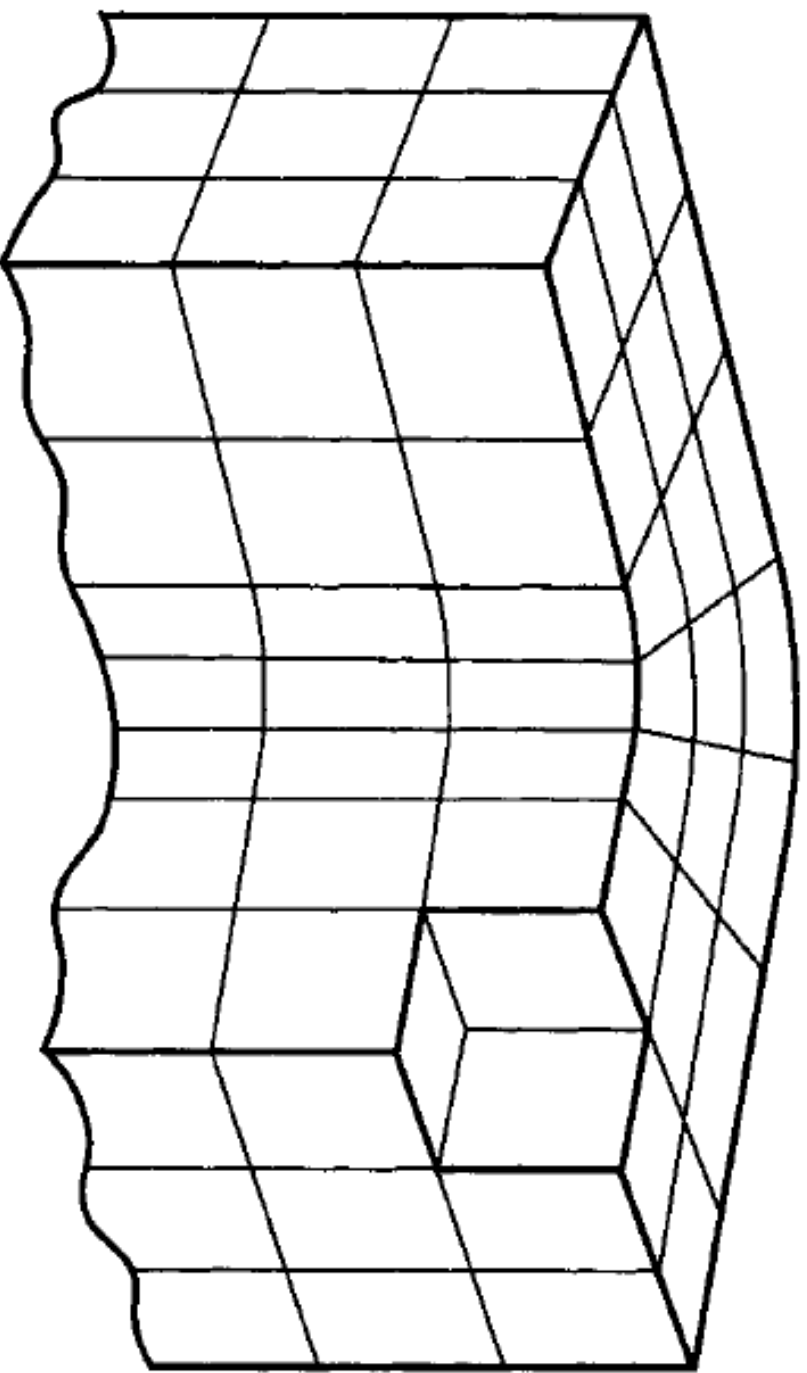


**Fig. 2.3.** A 'global' shape function –  $\tilde{N}_i$

# Shape functions

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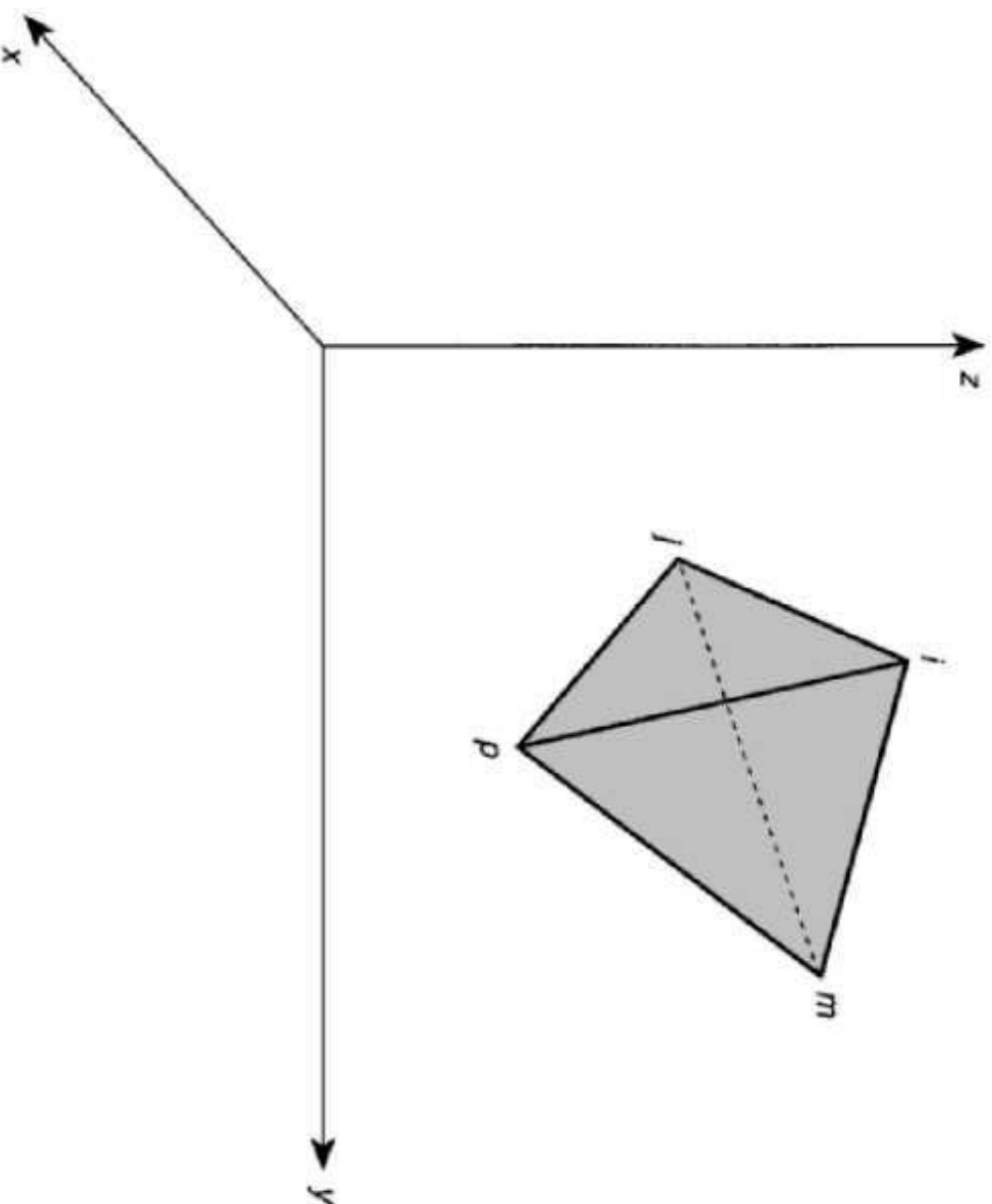




**Fig. 6.2** A systematic way of dividing a three-dimensional object into 'brick'-type elements.

## FEM applications

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**Fig. 6.1** A tetrahedral volume. (Always use a consistent order of numbering, e.g., for  $p$  count the other nodes in an anticlockwise order as viewed from  $p$ , giving the element as  $jimp$ , etc.)

- Solution Approximation

- basis functions  $u_X(x) = \sum_{i=1}^N \alpha_i \varphi_i(x)$

# Modeling

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- **Solution Approximation**

- basis functions  $u_X(x) = \sum_{i=1}^N \alpha_i \varphi_i(x)$

- **Algorithm**

- cut-off errors      iterations, expansions ...

# Modeling


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- **Solution Approximation**

- basis functions 
$$u_X(x) = \sum_{i=1}^N \alpha_i \varphi_i(x)$$

- **Algorithm**

- cut-off errors      iterations, expansions ...

- round-off errors      

$R_{comp}$  is not closed with respect to +, -, \*, / operations




# Modeling

---

- Solution Approximation

- basis functions  $u_X(x) = \sum_{i=1}^N \alpha_i \varphi_i(x)$

- Algorithm

- cut-off errors      iterations, expansions ...
- round-off errors      

$R_{comp}$  is not closed with respect to +, -, \*, / operations

$$\sqrt{x+1} - \sqrt{x} = \frac{1}{\sqrt{x+1} + \sqrt{x}}$$

## *Modeling*

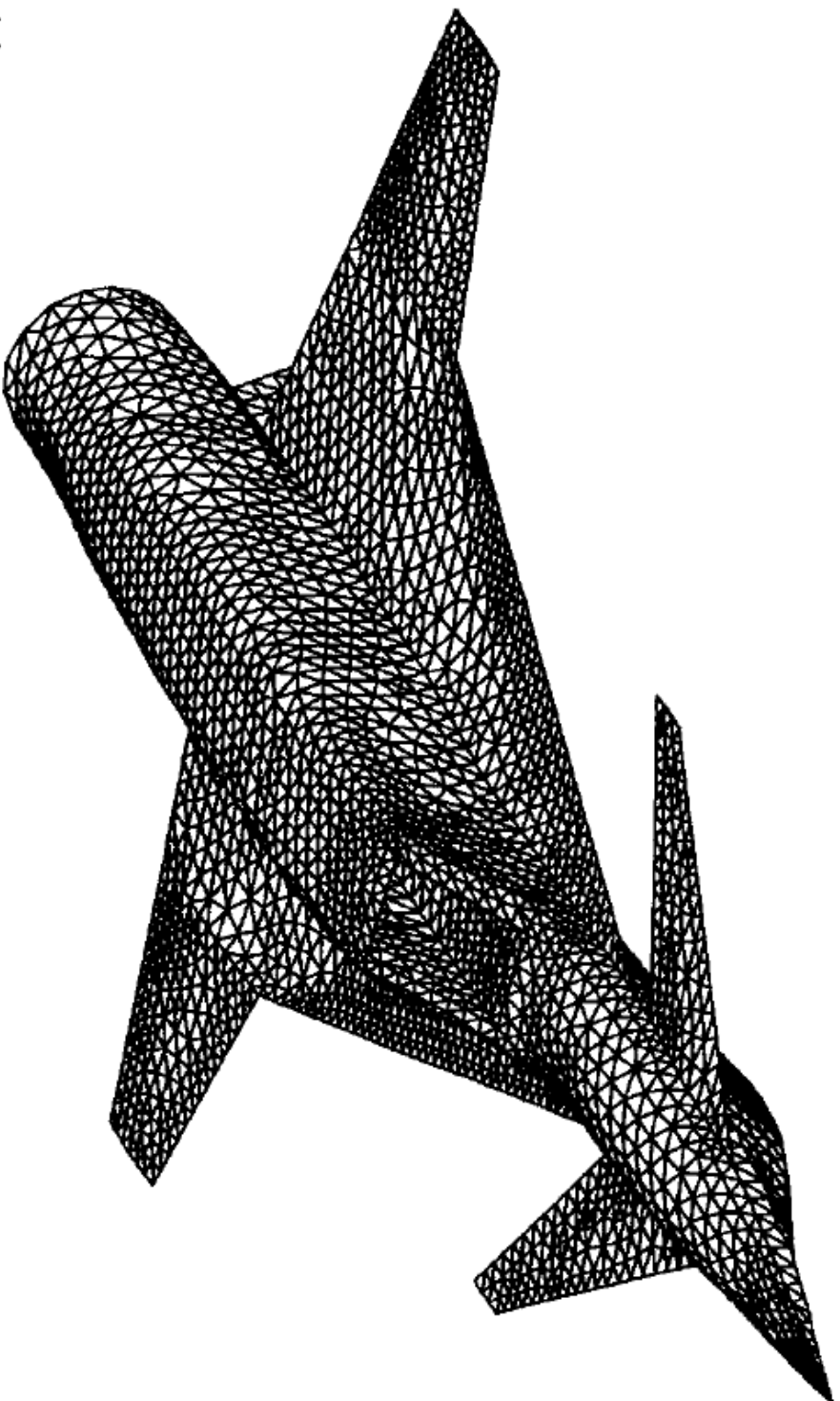
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- Other error sources
  - Insufficient user knowledge  
inadequate model  
inappropriate mesh  
improper result interpretation
  - Bug in the code
  - Wrong data
  - ● ● ●

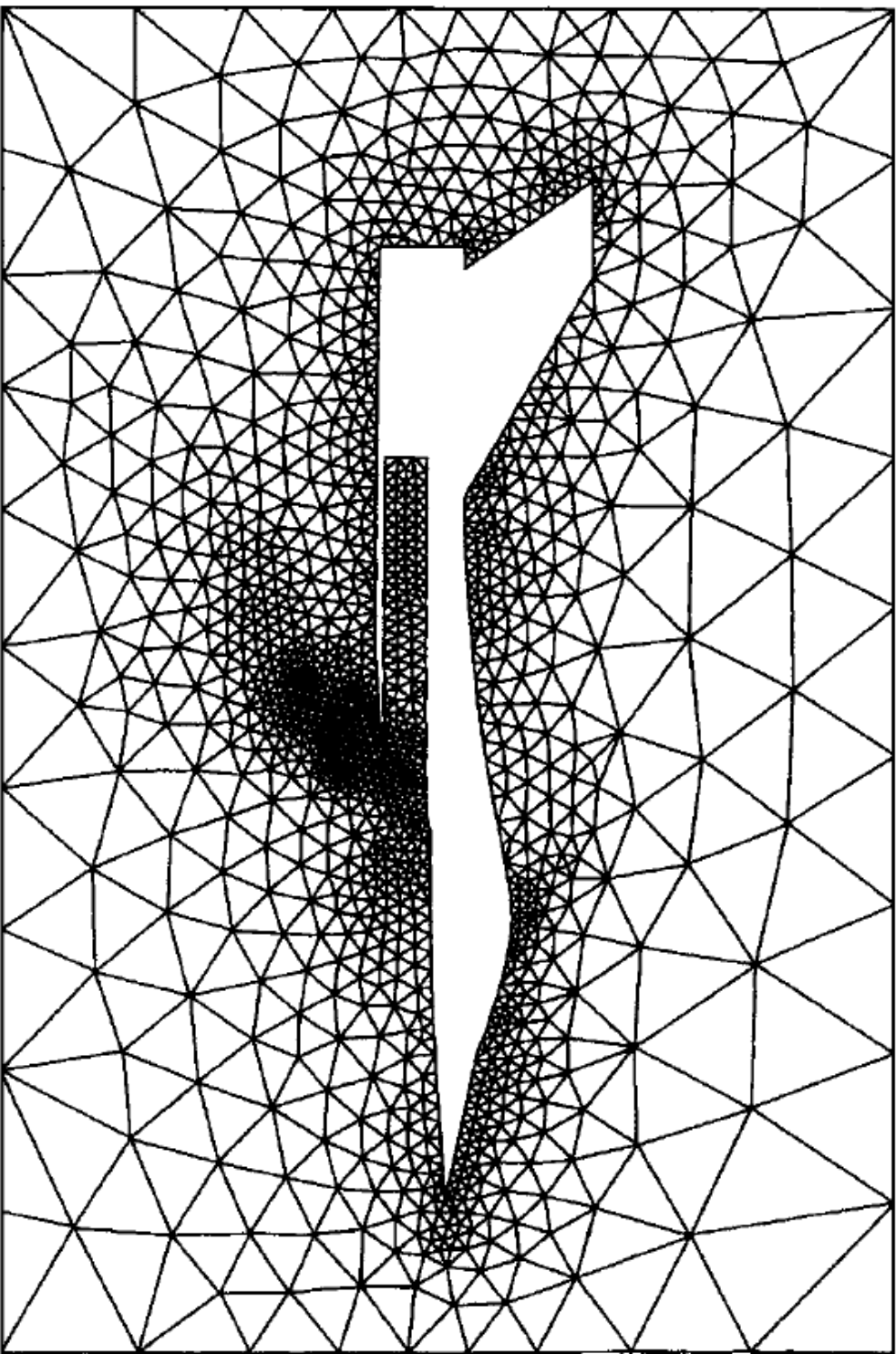
## Modeling

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- Other error sources
  - Insufficient user knowledge  
inadequate model  
inappropriate mesh  
improper result interpretation
  - Bug in the code
  - Wrong data
  - ● ● ● ●
- Mathematics in modeling
  - If we are not sure that a solution exists then what we try to approximate numerically?
  - If we do not know which class of functions the solution belongs to, then we cannot properly define its approximation and the measure for the accuracy
  - Classical error control theory is mainly focused on approximation errors



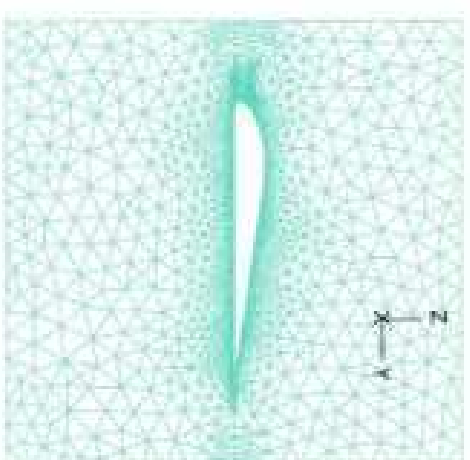
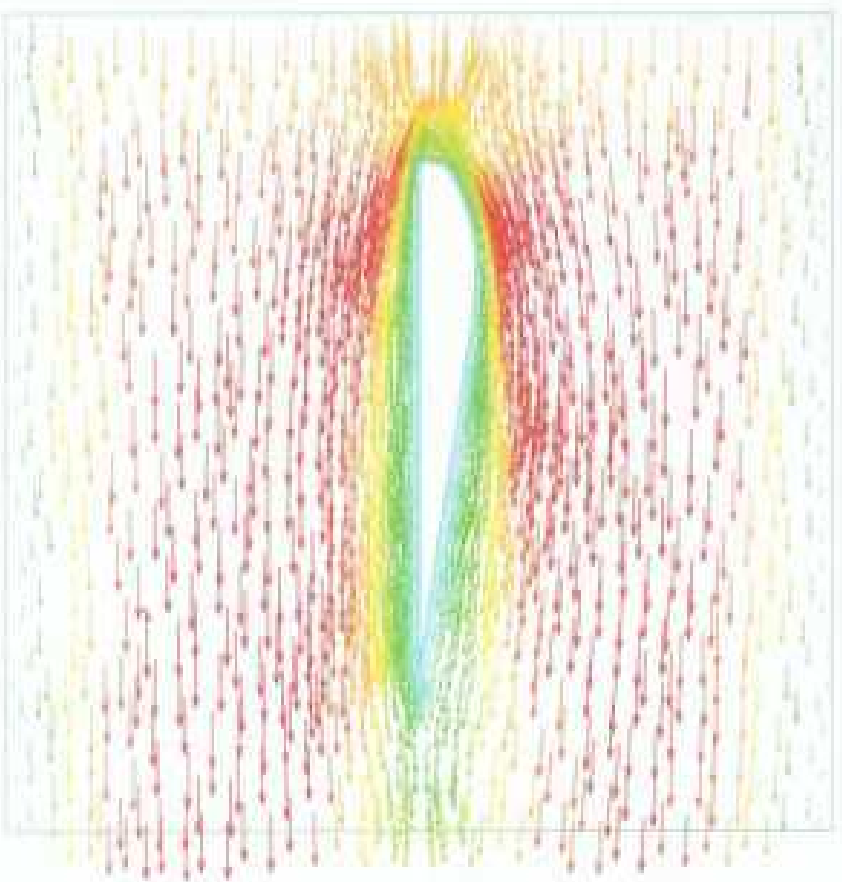
(a)



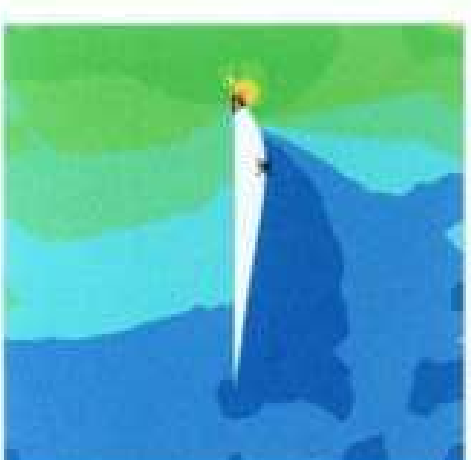
(b)

# FEM applications

ADINA



MAXIMUM  
Δ 70.45  
MINIMUM  
# -12.33



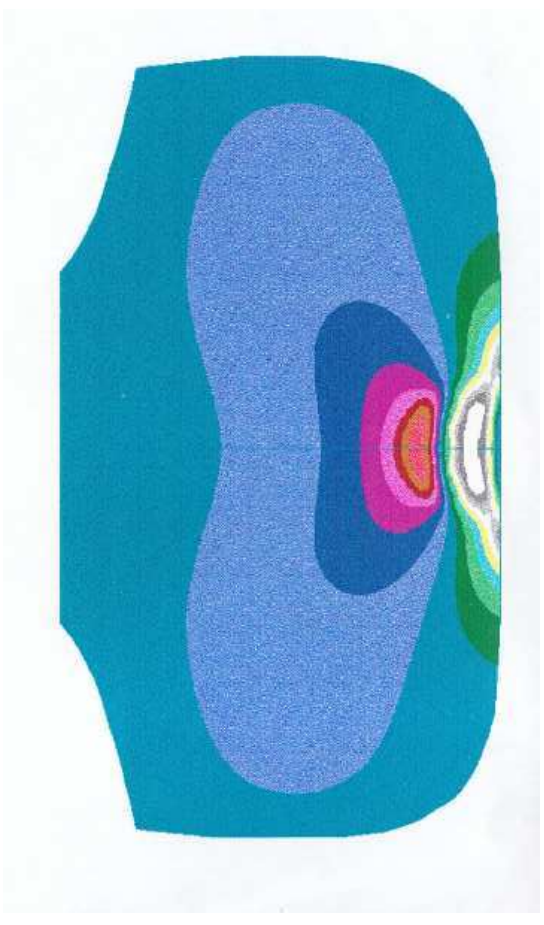
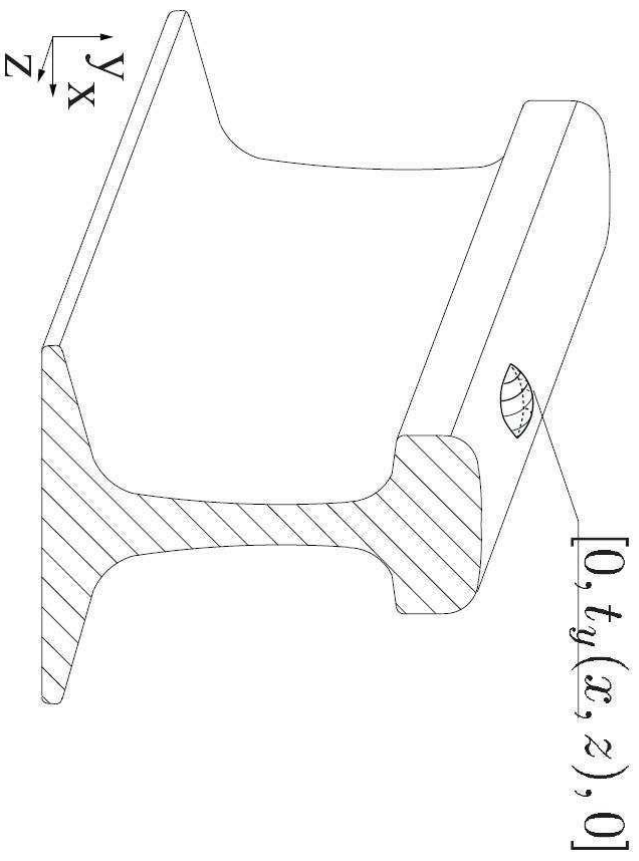
SMOOTHED  
PRESSURE  
RST CALC  
TIME 1.000

68.00
54.00
42.00
30.00
18.00
6.00
-8.00

Air flow around an airplane wing

## *FEM applications*

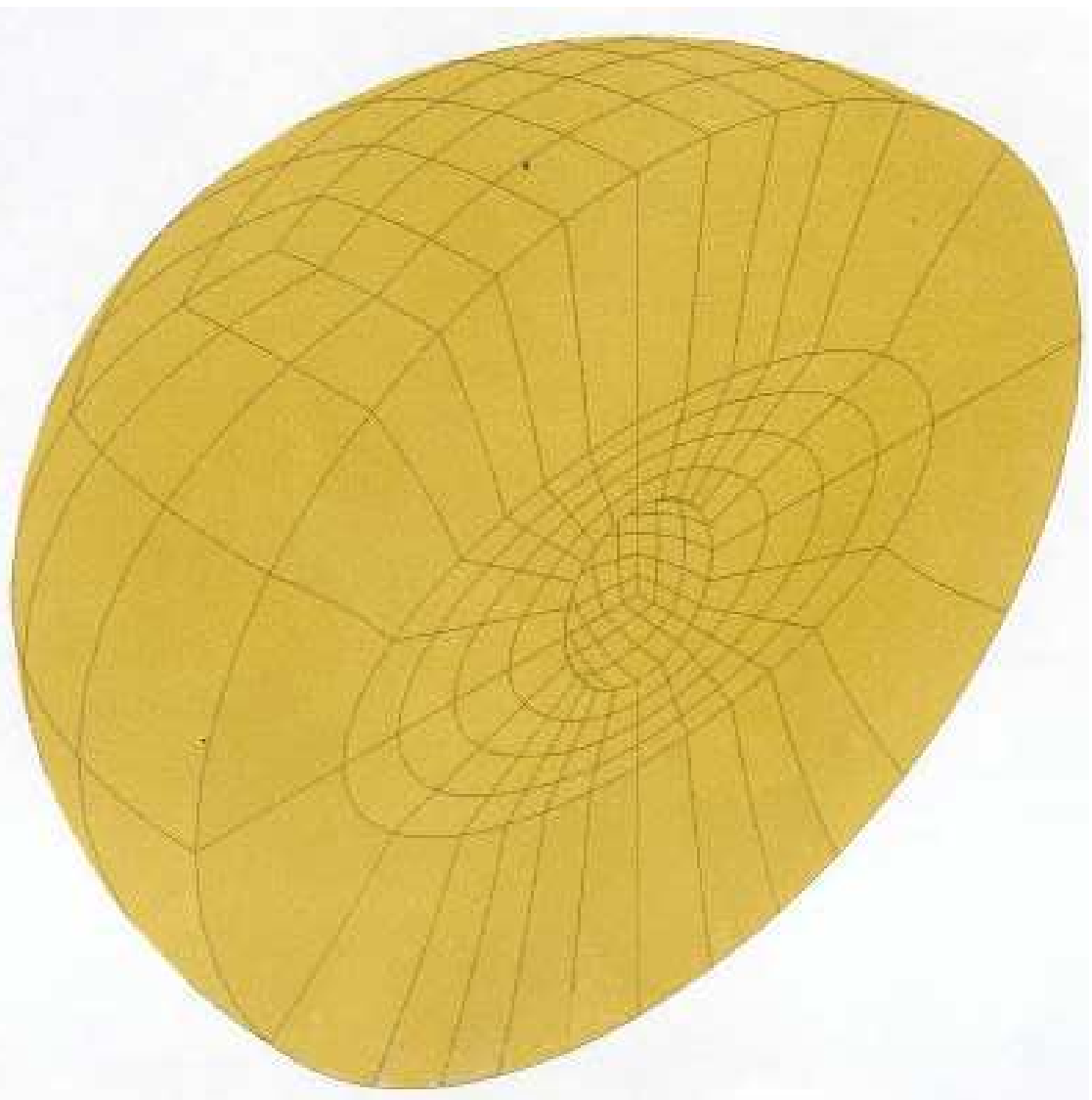
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Longitudinal residual stress component in railroad rail

## *FEM applications*

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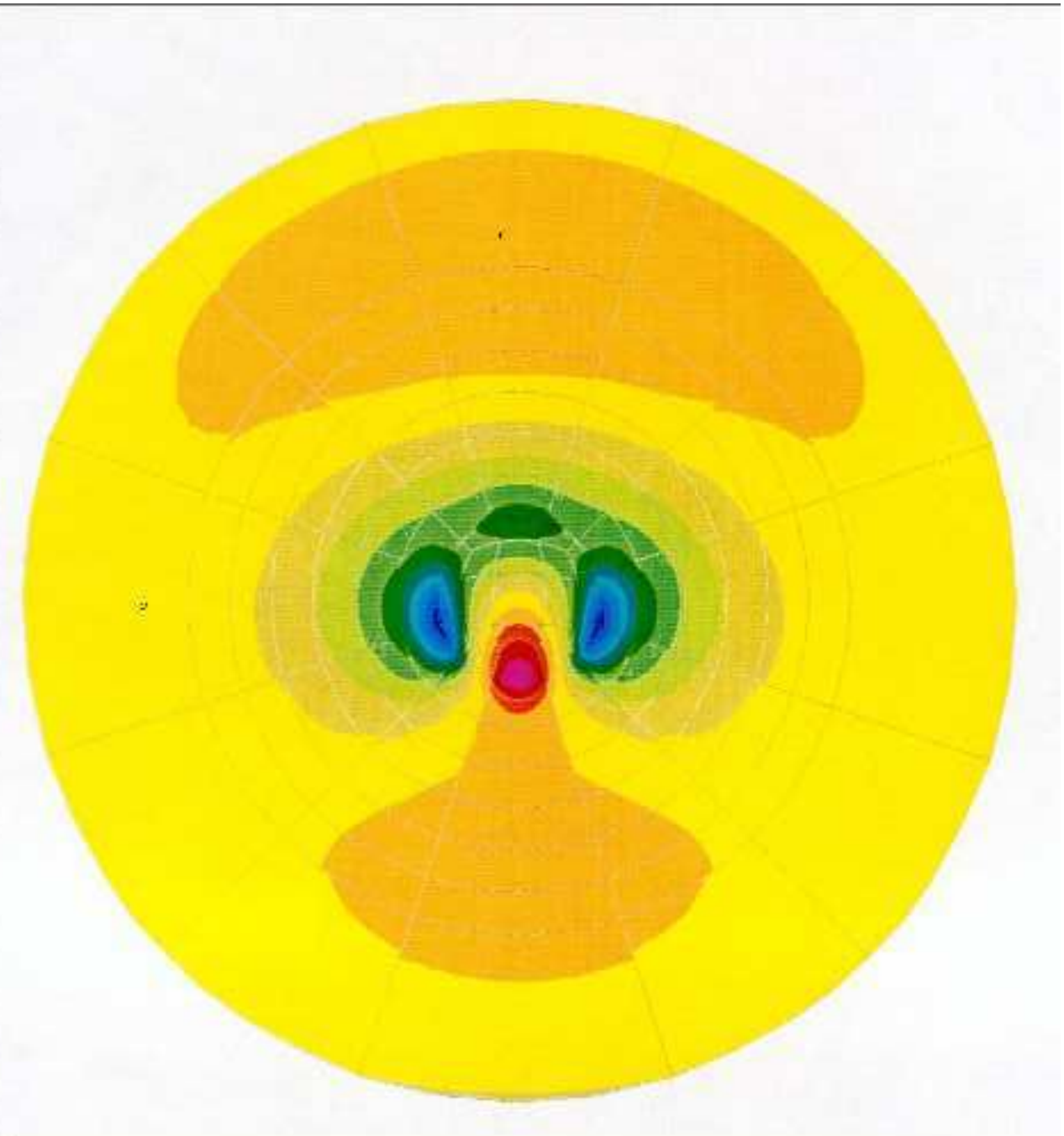
Scattering of electromagnetic waves

Exterior of a ball discretized by finite and infinite elements

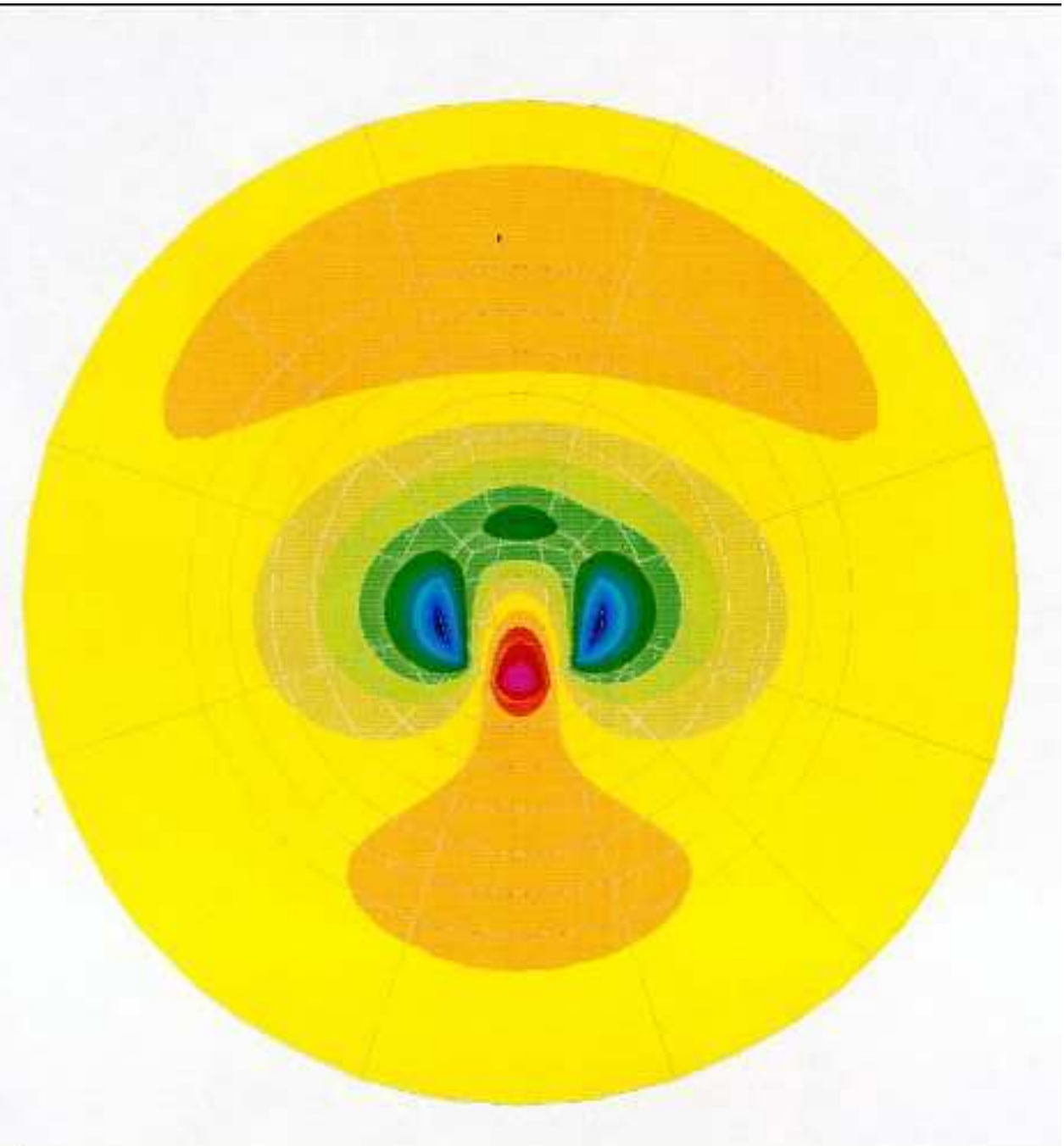


## *FEM applications*

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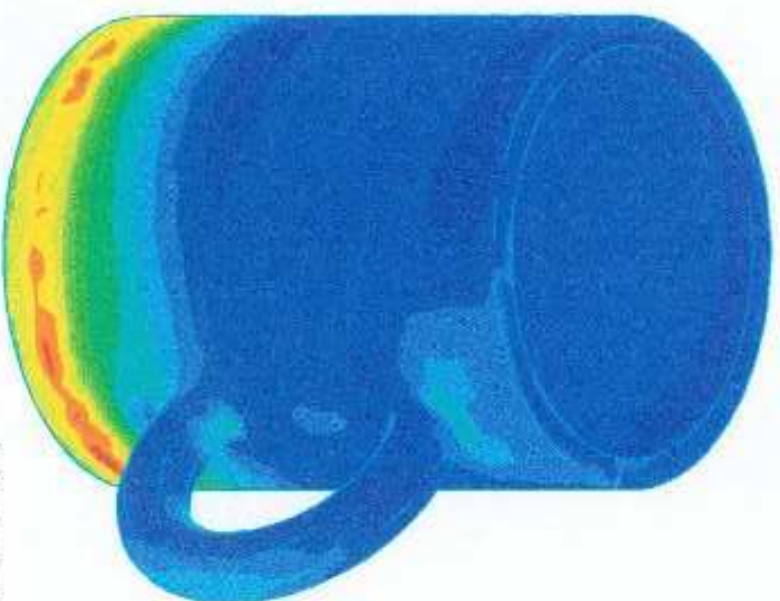
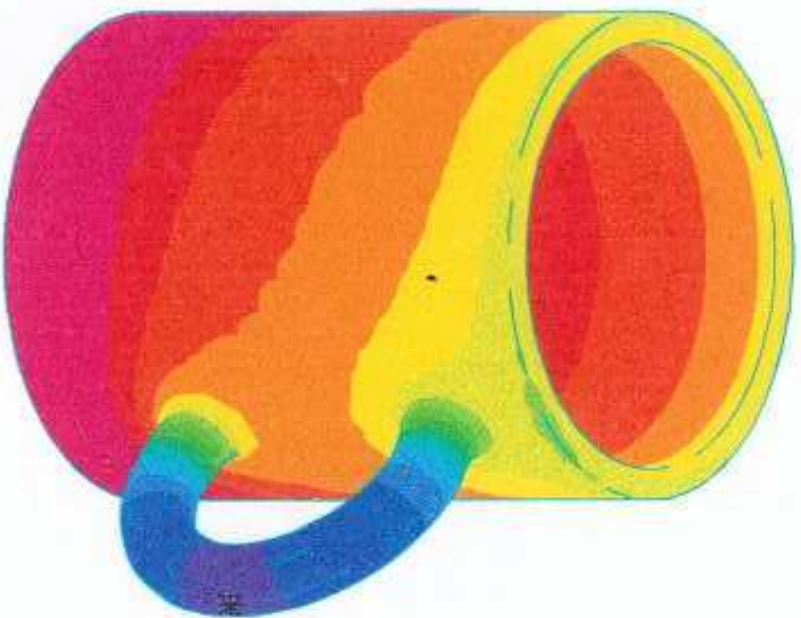
FEM approximation of electric field



Exact electric field

# FEM applications

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Heat transfer

# Modeling

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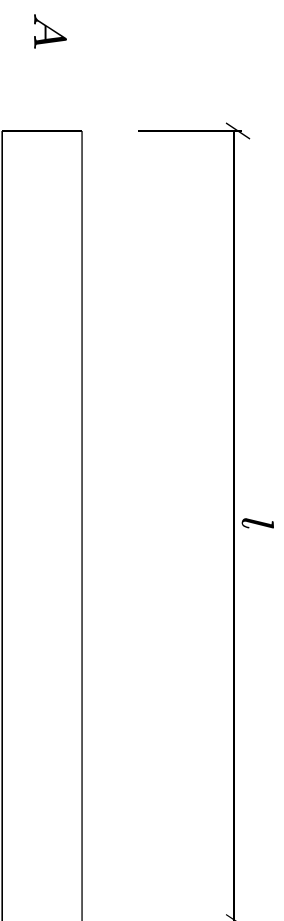
Columns in Syria



Model

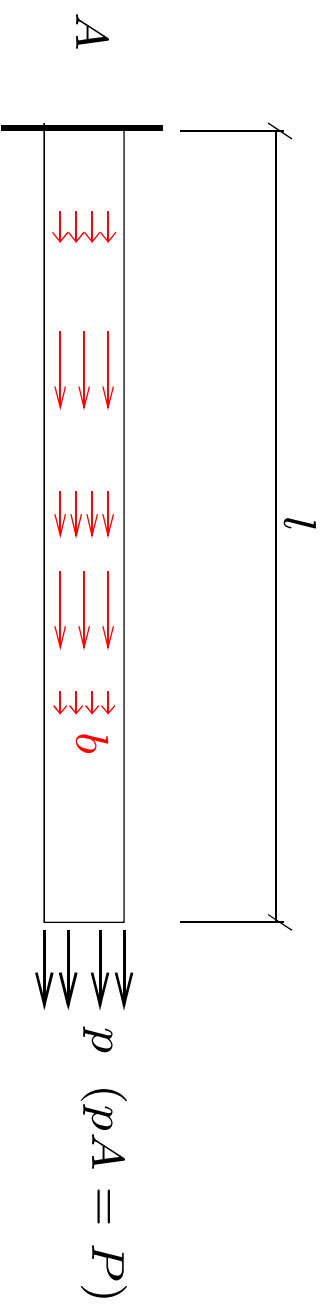
## *Problem formulation*

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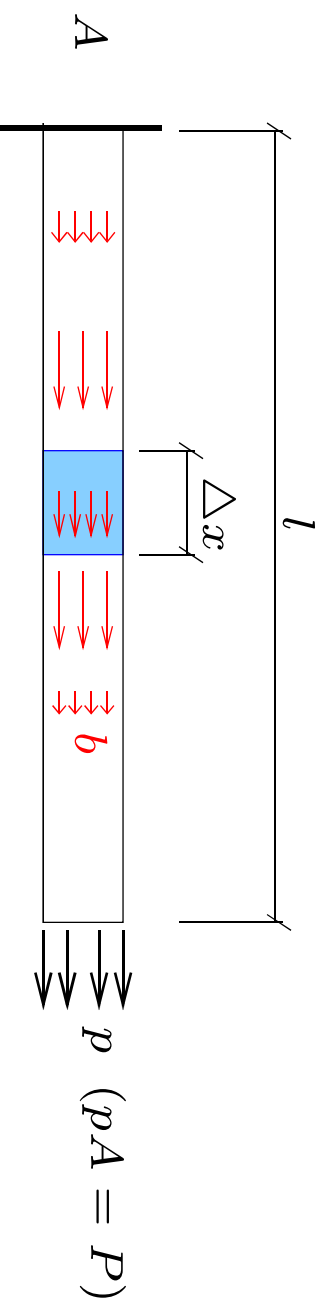
## Problem formulation

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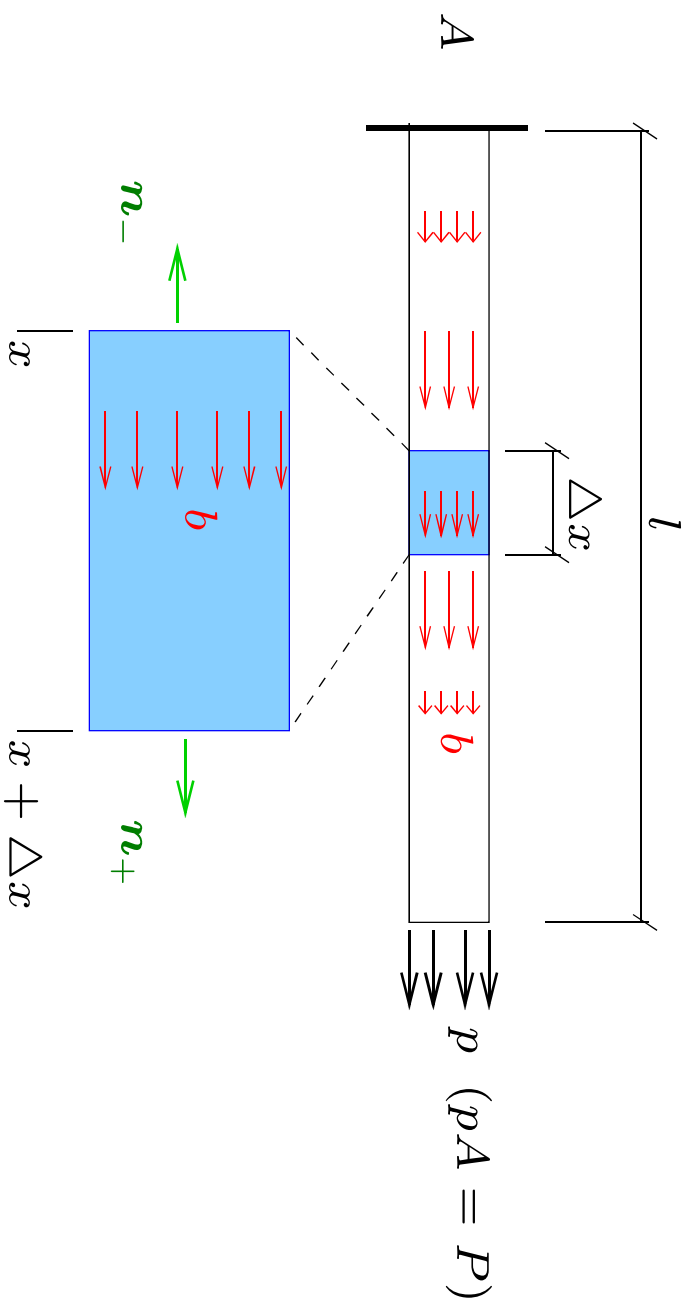
## Problem formulation

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# Problem formulation

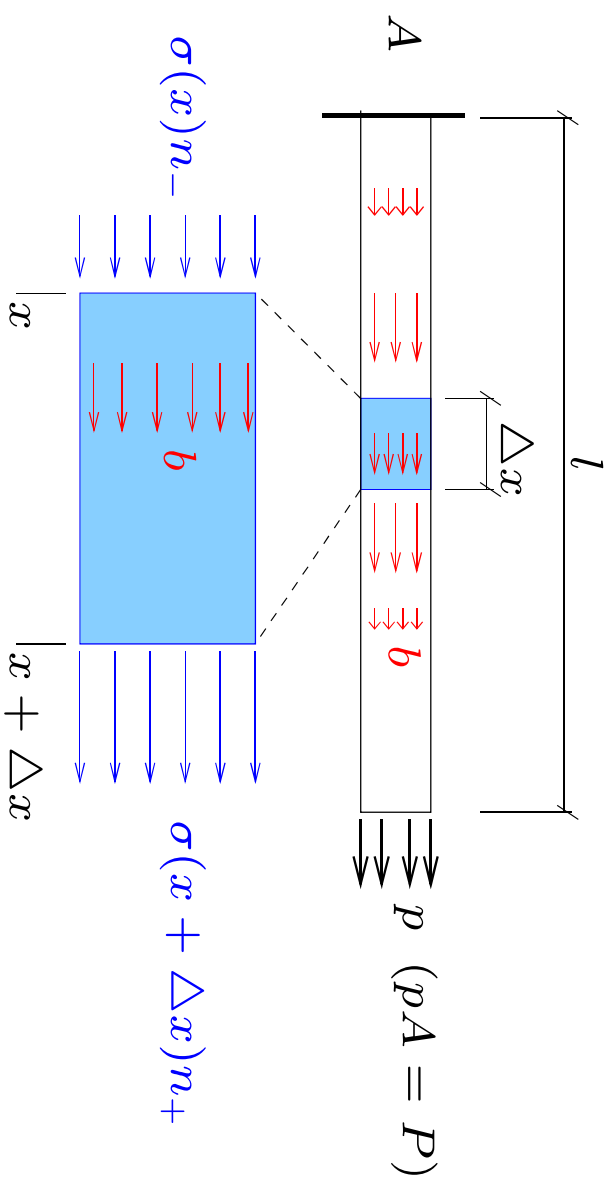
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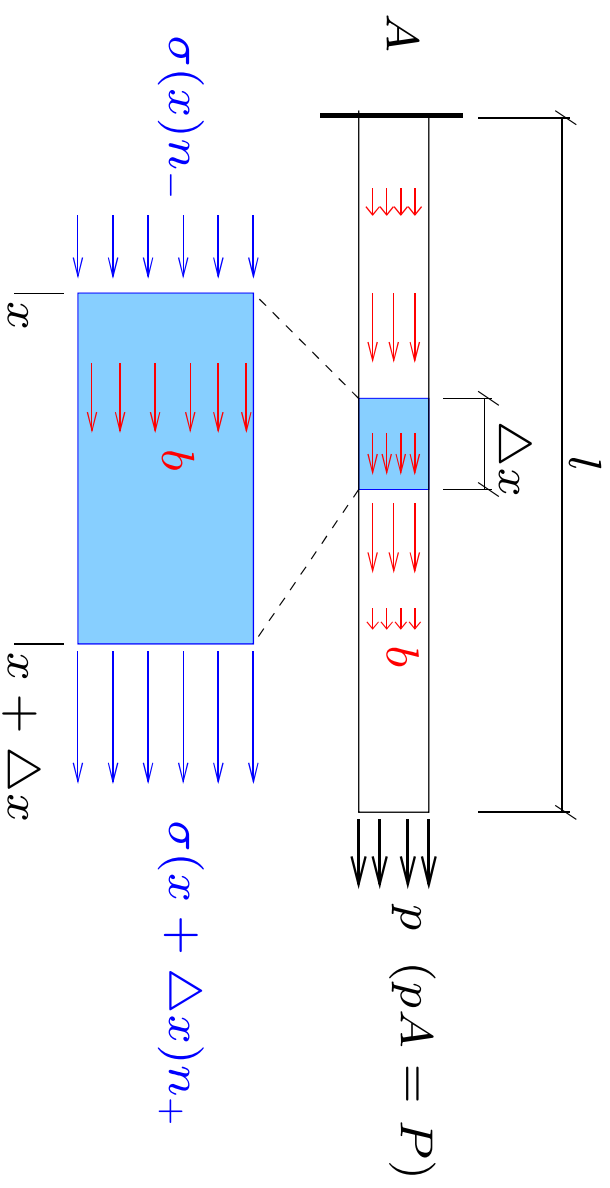


# Problem formulation

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## Problem formulation



$$\sigma = \sigma(x), \quad b = b(x) \quad \rightarrow \quad \sigma(x)A = N(x), \quad b(x)A = q(x)$$

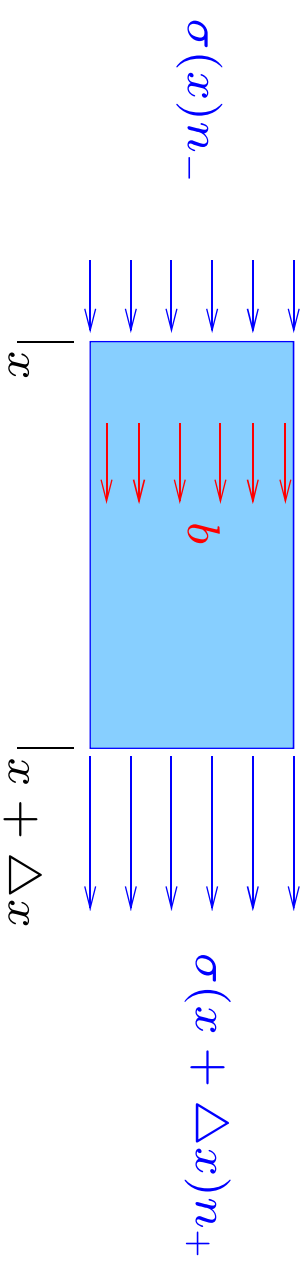
$$\text{elastic material} \quad \rightarrow \quad \sigma(x) = E\varepsilon(x)$$

$$\text{small displacement gradients} \quad \rightarrow \quad \varepsilon(x) = \frac{du}{dx} \quad \rightarrow \quad \sigma = E \frac{du}{dx}$$

*short range of intermolecular forces*

## Problem formulation

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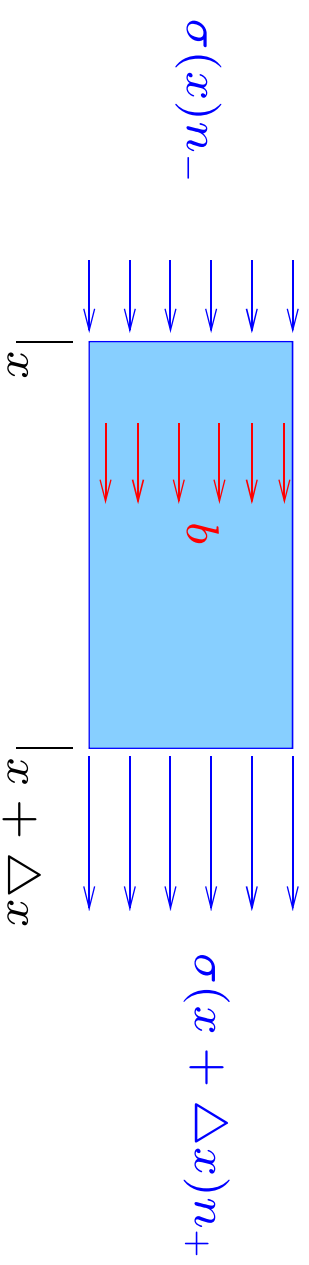


**Momentum Conservation Principle** (Second Newton's Law of Motion)

→ **Equilibrium Equations**

## Problem formulation

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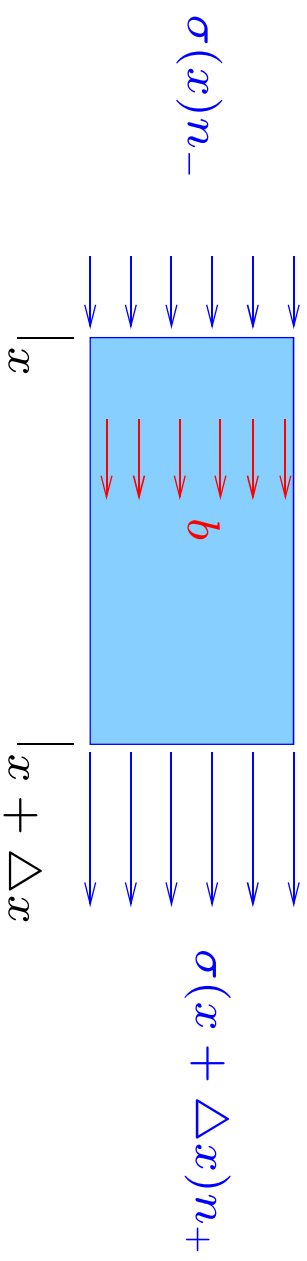
**Momentum Conservation Principle** (Second Newton's Law of Motion)

→ **Equilibrium Equations**

$$A\sigma(x)n_- + \int_x^{x+\Delta x} q(y) dy + A\sigma(x + \Delta x)n_+ = 0 \quad \forall \omega \subset (0, l)$$

## Problem formulation

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**Momentum Conservation Principle** (Second Newton's Law of Motion)

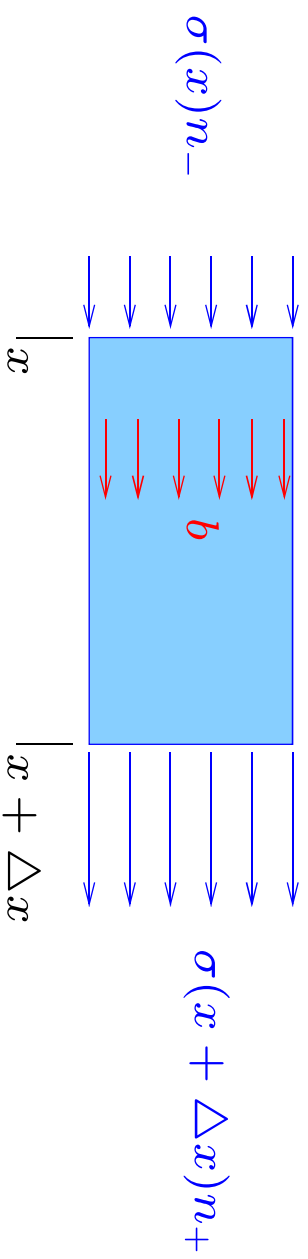
→ **Equilibrium Equations**

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$$n_- = -1, \quad n_+ = 1$$

## Problem formulation

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**Momentum Conservation Principle** (Second Newton's Law of Motion)

→ **Equilibrium Equations**

$$A\sigma(x)n_- + \int_x^{x+\Delta x} q(y) dy + A\sigma(x + \Delta x)n_+ = 0 \quad \forall \omega \subset (0, l)$$

$$n_- = -1, \quad n_+ = 1$$

**Find  $u(x)$  such that:**

$$AE \frac{du}{dx}(x + \Delta x) - AE \frac{du}{dx}(x) = - \int_x^{x+\Delta x} q(y) dy \quad \forall \omega \subset (0, l) + \text{b.c.}$$

→ **FVM**

## Problem formulation

---

- Taylor formula:  $\exists \xi : \frac{du}{dx}(x + \Delta x) = \frac{du}{dx}(x) + \frac{d^2u}{dx^2}(\xi) \Delta x$  (if  $u''$  exists)
- Mean value theorem:  $\exists \eta : \int_x^{x+\Delta x} q(y) dy = q(\eta) \Delta x$  (if  $q$  is continuous)

## Problem formulation

---

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- $\Delta x \rightarrow 0$



## Problem formulation

---

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- Mean value theorem:  $\exists \eta : \int_x^{x+\Delta x} q(y) dy = q(\eta) \Delta x$  (if  $q$  is continuous)
- $\Delta x \rightarrow 0$

Find  $u(x) \in C^2([0, l])$  such that:

$$\begin{cases} AE \frac{d^2u}{dx^2} = -q(x) & \forall x \in (0, l) \\ u(0) = 0 \\ AE \frac{du}{dx}(l) = P \end{cases}$$

→ **FDM**

**Thank you**